6″ [152 mm]   4″ [100 mm]

The SR1J is a rugged, low-cost, easy to install high performance string pots built for wet environments and outdoor applications.

The SR1J comes in two ranges: 0-125 inches and 0-175 inches and is the perfect low-cost J1939 CANbus solution for mobile applications such as mobile crane outrigger position or hydraulic lifts. Every unit ships with a handy mounting bracket giving the user the ultimate flexibility to easily orient the measuring cable to one of four different directions.
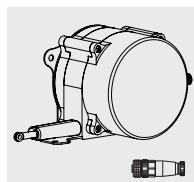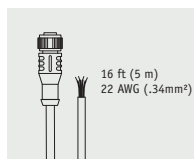
Ordering Information:
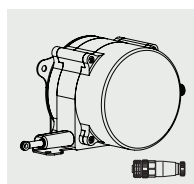
Order No.
SR1J-125
- 125-inch stroke range
- CANBus J1939 Communication
- 5-pin M12 field installable mating plug
- mounting bracket

Order No.
SR1J-175
- 175-inch stroke range
- CANBus J1939 Communication
- 5-pin M12 field installable mating plug
- mounting bracket

Order No.
9036810-0030

16 ft (5 m)
22 AWG (.34mm²)

for short-run connections, optional 16-ft (5 m) long cordset with 5-pin M12 mating plug.

SR1J
Cable Actuated Sensor
Industrial • CANBus J1939

Two Available Stroke Ranges: 0-125 in & 0-175 in.

Rugged Polycarbonate Enclosure • Simple Installation

Designed for Outdoor & IP67 environments

IN STOCK FOR QUICK DELIVERY!

Specifications

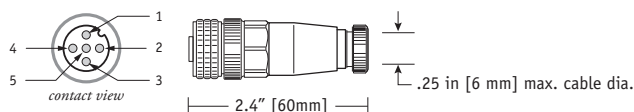|	
Full Stroke Range, SR1J-125	125 inches (3175 mm), maximum
Full Stroke Range, SR1J-175	175 inches (4445 mm), maximum
Repeatability	.05% FS.
Resolution	12-bit
Input Voltage	10-36 VDC
Input Current	100 mA, max.
Maximum Velocity	80 inches (2 meters) per second
Maximum Acceleration	10 g (retraction)
Measuring Cable Tension	23 oz. (6,4 N) ±30%
Sensor	plastic-hybrid precision potentiometer
Cycle Life	250,000 (potentiometer)
Enclosure	polycarbonate
Measuring Cable	.031-inch dia. bare stainless rope
Electrical Connection	M12 Connector (mating plug included)
Environmental Suitability	NEMA 6, IP67
Operating Temperature	-40˚ to 185˚ F (-40˚ to 85˚ C)
Weight	2.5 lbs. (1.3 Kg)

CANbus Specifications

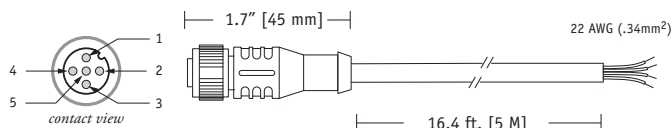|	
Communication Profile	CANbus SAE J1939
Protocol	Proprietary B
Node ID	Adjustable via dipswitch (0-63), default set to 0
Baud Rate Options	125K (default), 250K, 500K
Data Rate Options	5ms (default), 20ms, 50ms, 100ms

Electrical Connection

output signal	connector pin	colorcode (cordset)
n/c	1	brown
10...36 VDC	2	white
common	3	blue
CAN high	4	black
CAN low	5	green/yellow

M12 Connector (included)

contact view

.25 in [6 mm] max. cable dia.

2.4" [60mm]

16 ft. Cordset (optional)

contact view

1.7" [45 mm]

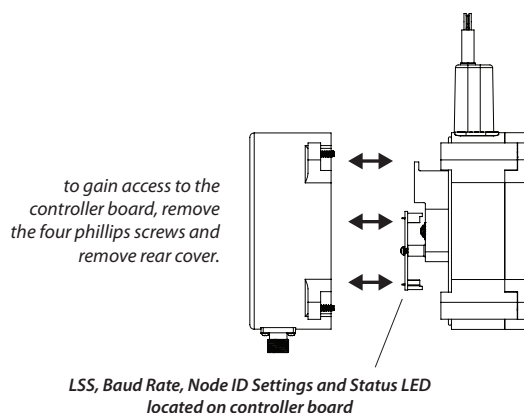22 AWG (.34mm^2)

16.4 ft. [5 M]

Internal Controller Board

LSS, Baud Rate and Node ID settings:

LSS, Baud Rate and Node ID settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body.

Follow the instructions on the following pages for desired settings and reinstall sensor cover.

to gain access to the controller board, remove the four phillips screws and remove rear cover.

LSS, Baud Rate, Node ID Settings and Status LED located on controller board

Baud, Node ID and Data Rate:

Baud Rate, Node ID and Data Rate settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body. Be careful not to damage the small gage wires that connect the controller board to the connector mounted directly to the rear cover.
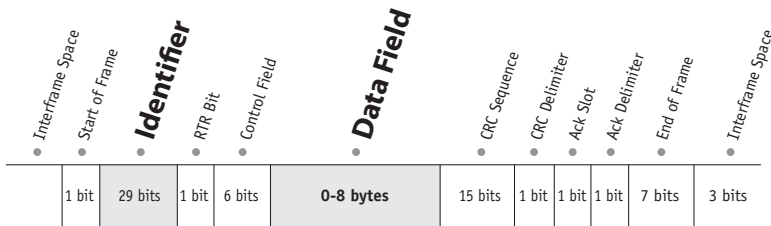
node ID options 0–63 (0x00–0x3F)

node ID Dec.	Hex	SW1 (2^0)	SW2 (2^1)	SW3 (2^2)	SW4 (2^3)	SW5 (2^4)	SW6 (2^5)
0	0x00	off	off	off	off	off	off
1	0x01	on	off	off	off	off	off
2	0x02	off	on	off	off	off	off
3	0x03	on	on	off	off	off	off
...	...	...	...	...	...	...	...
62	0x3E	off	on	on	on	on	on
63	0x3F	on	on	on	on	on	on

BAUD rate options

baud rate	SW7	SW8
125 kbps	off	off
250 kbps	on	off
500 kbps	off	on

Data Rate options

Data Rate	SW9	SW10
5 ms	off	off
20 ms	on	off
50 ms	off	on
100 ms	on	on

I/O Format:

	Start of Frame	Identifier	RTR Bit	Control Field	Data Field	CRC Sequence	CRC Delimiter	Ack Slot	Ack Delimiter	End of Frame	Interframe Space
1 bit	1 bit	29 bits	1 bit	6 bits	0-8 bytes	15 bits	1 bit	1 bit	1 bit	7 bits	3 bits

Position Data Overview

0x000 (out of range) 0x006 (0% fs.) 0xFE5 (100% fs.) 0xFFF (out of range)

Nominal Full Stroke Range Position Values

position data …

endpoint tolerance 0x002 – 0x00A 0xFCC – 0xFFC endpoint tolerance

spring loaded cable reel

cable extension

Identifier:

	Message Priority		Future Use		J1939 Reference Proprietary B								Data Field Type*								Not Used		Node ID**					
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –		0			F			F			5			3			3				F								

*Sensor field data can be factory set to customer specific value.   **Customer defined, set via Dips 1-6. Bit values shown for example only, see **Address Setting** below.

Data Field:

B_0 = LSB current measurement count byte
B_1 = MSB current measurement count byte

B_2 = not used
B_3 = not used

B_4 = error flag
B_5 = error flag

B_6 = LSB velocity data byte
B_7 = MSB velocity data byte

Velocity Data		Error Flags		Not Used		Current Measurement Count	
B_7	B_6	B_5	B_4	B_3	B_2	B_1	B_0

Current Measurement Count

| B_7 | B_6 | B_5 | B_4 | B_3 | B_2 | B_1 | B_0 |

The **C**urrent **M**easurement **C**ount (**CMC**) is the output data that indicates the present position of the measuring cable. The CMC is a 12-bit value that occupies bytes B_0 and B_1 of the data field. B_0 is the **LSB** (least significant byte) and B_1 is the **MSB** (most significant byte).

The **CMC** starts at **0x006** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFE5**.   This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 4061 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\frac{CMC - 6}{4063} \right) \times \text{full stroke range}$$

Sample Conversion:

If the full stroke range is **125 inches** and the current position is **0x4FF** (1279 Decimal) then,

$$\left(\frac{1279 - 6}{4061} \right) \times 125 = 39.2 \text{ inches}$$

Error Flags

| B_7 | B_6 | B_5 | B_4 | B_3 | B_2 | B_1 | B_0 |

RED and GREEN Indicator LEDS (controller board)

0x00 (GREEN - ON, RED - OFF) indicates the sensor is operating within normal calibrated limits.

0x33, 0x55, 0xAA, 0xCC (RED or GREEN - FLASHING) indicates sensor is at or beyond it's calibrated measurment range. Should any of these conditions occur within calibrated range, return unit to factory for evaluation or service.

| B_7 | B_6 | B_5 | B_4 | B_3 | B_2 | B_1 | B_0 |

Velocity

Data in bytes B_7 - B_6 is the change in the **CMC** (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.

B_7 - B_6 HEX (Decimal)	max "reverse" velocity / max "forward" velocity	Velocity (cts./100 msec.)
0x000 (0)		– 2047 counts
0x7FF (2047)		"0" counts (no change)
0xFFF (4095)		2047 counts

Velocity Calculation

$$\left(\frac{\text{count change} - 2047}{.1 \text{ sec. time period}} \right) \times \left(\frac{\text{full stroke range}}{4063} \right)$$

Sample Calculations

Cable Extension (positive direction):
$B_7..B_6$ = **0x8D3** (2259Dec), **full stroke = 125 in.**

$$\left(\frac{2259 - 2047}{.1 \text{ sec}} \right) \times \left(\frac{125 \text{ in.}}{4063} \right) = 65.22 \text{ in. / sec.}$$

Cable Retraction (negative direction):
$B_7..B_6$ = **0x7D0** (2000Dec), **full stroke = 125 in.**

$$\left(\frac{2000 - 2047}{.1 \text{ sec}} \right) \times \left(\frac{125 \text{ in.}}{4063} \right) = -14.46 \text{ in. / sec.}$$
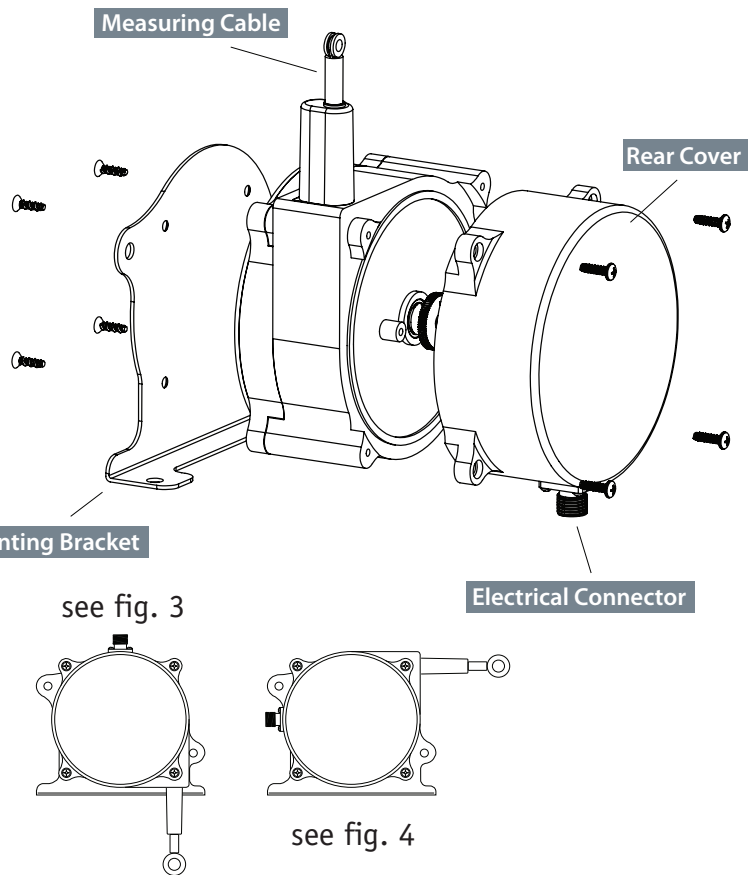
Changing the Cable Exit

Changing Measuring Cable Exit
To change the direction of the measuring cable, remove the 4 mounting bracket screws and rotate bracket to one of four available positions. See figures 1 - 4 on the following pages for mounting dimensions.

Changing Electrical Connector Direction
To change the position of the electrical connector, remove the 4 rear cover screws and carefully separate rear cover from the sensor body.

Rotate the rear cover to desired position being careful to not tangle the wiring harness that runs to the connector.
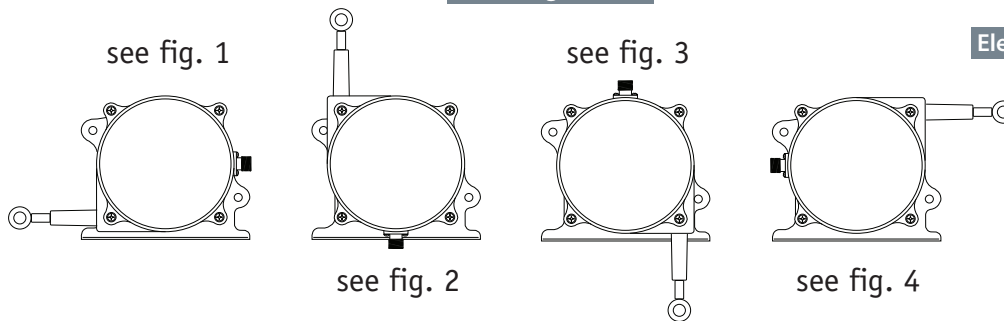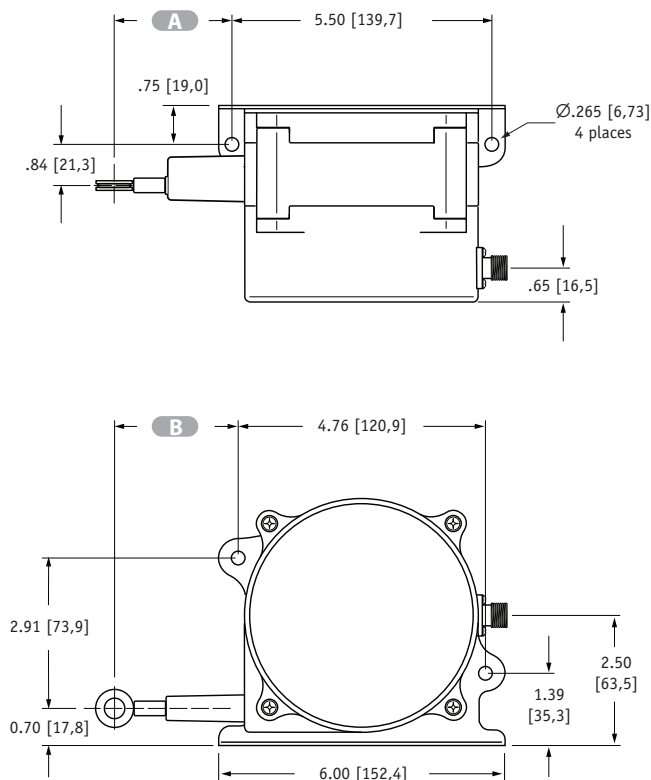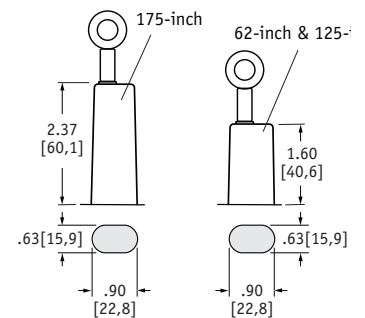
Measuring Cable

Rear Cover

Mounting Bracket

Electrical Connector

Cable Exit Direction Options

see fig. 1

see fig. 2

see fig. 3

see fig. 4

Fig. 1 - Outline Drawing (as shipped)

A
5.50 [139,7]
.75 [19,0]
Ø.265 [6,73] 4 places
.84 [21,3]
.65 [16,5]

Model	A	B
125-inch	2.00 ±.13 [50,8 ±3,3]	2.37 ±.13 [60,22 ±3,3]
175-inch	2.87 ±.13 [72,8 ±3,2]	3.24 ±.13 [82.2 ±3,2]

Cable Guide Detail
175-inch
62-inch & 125-inch
2.37 [60,1]
1.60 [40,6]
.63[15,9]
.63[15,9]
.90 [22,8]
.90 [22,8]

B
4.76 [120,9]
2.91 [73,9]
0.70 [17,8]
2.50 [63,5]
1.39 [35,3]
6.00 [152,4]

3.85 [97,8] max.
Ø 4.49 [114,0]
1.18 [30,0]

Eyelet Detail
.20 [5,1]
Ø.40 [10,2]
Ø.79 [20,1]
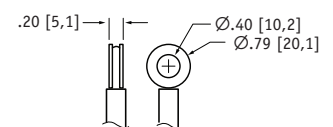
units are in **inches [mm]**   tolerances are ± .04 [1,0] unless otherwise noted

Fig. 2 - "Up" Cable Exit Direction

Model	A
125-inch	3.64 ±.13 [92,5 ±3,3]
175-inch	4.54 ±.13 [115,3 ±3,3]

5.50 [139,7]
.96 [24,4]
.75 [19,0]
.84 [21,3]
Ø.265 [6,73] 4 places
.60 [15,2]
A
3.61 [91,7]
1.391 [35,32]
4.76 [120,9]
6.00 [152,4]
1.59 [40,4]
Ø 4.49 [114,0]
.65 [16,5]
1.18 [30,0]
3.85 [97,8] max.
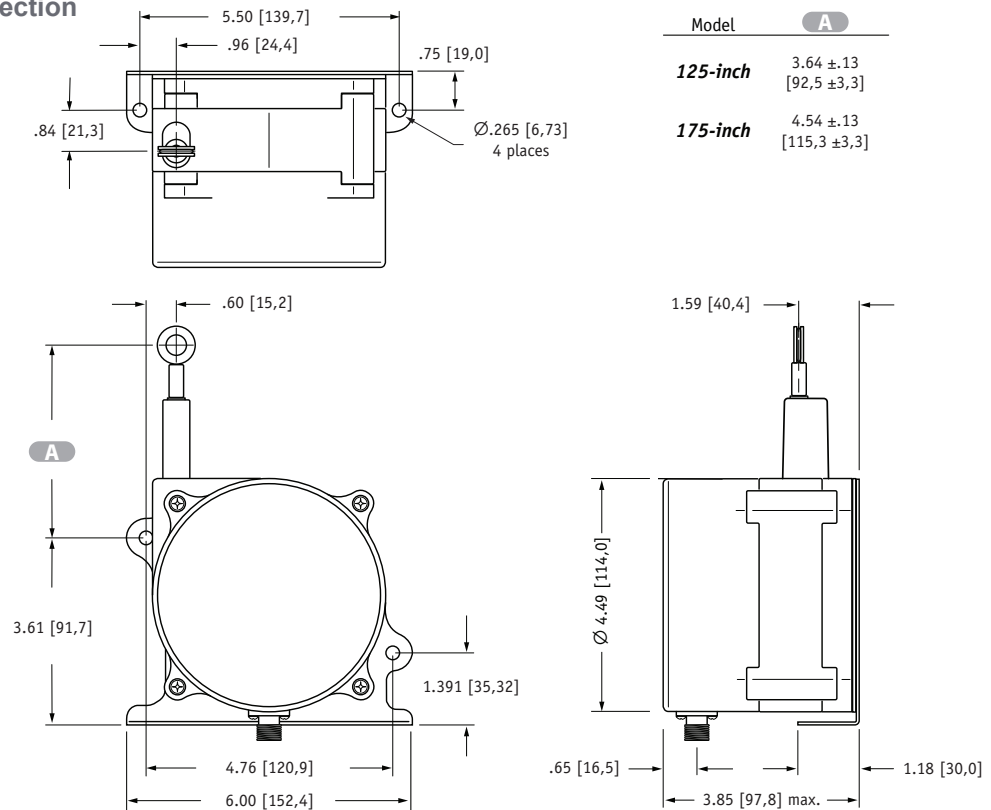
Fig. 3 - "Down" Cable Exit Direction

Model	A
125-inch	2.25 ±.13 [57,2 ±3,3]
175-inch	3.17 ±.13 [80,5 ±3,3]

5.50 [139,7]
.95 [24,1]
.75 [19,0]
Ø.265 [6,73] 4 places
.84 [21,3]
bottom cable exit location
4.76 [120,9]
3.61 [91,7]
1.39 [35,3]
.58 [14,7]
3.85 [97,8] max.
.65 [16,5]
Ø 4.49 [114,0]
1.18 [30,0]
1.59 [40,4]
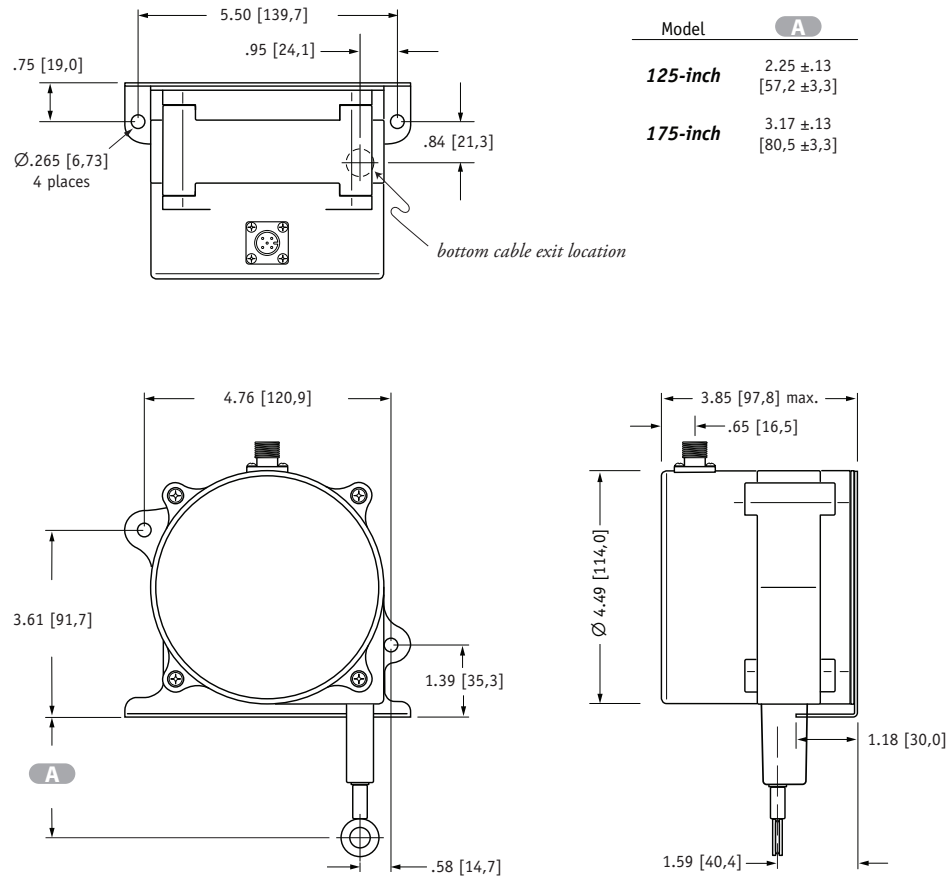
Fig. 4 - "Rear" Cable Exit Direction

Model	A	B
125-inch	2.00 ±.13 [50,8 ±3,3]	2.37 ±.13 [60,22 ±3,3]
175-inch	2.87 ±.13 [72,8 ±3,2]	3.24 ±.13 [82.2 ±3,2]

5.50 [139,7] A

Ø.265 [6,73] 4 places

.75 [19,0]

.84 [21,3]

.65 [16,5]

4.76 [120,9] B

3.61 [91,7]

2.50 [63,5]

6.00 [152,4]

4.30 [109,2]

1.39 [35,3]

3.85 [97,8] max.

1.59 [40,4]

Ø 4.49 [114,0]

1.18 [30,0]

units are in **inches [mm]**   tolerances are ± .04 [1,0] unless otherwise noted